



## Abstract

- A Redfish policy resource can be created to form control loops with the existing sensor and control resources. A policy management model has been proposed to manage these policy resources and allow Redfish clients to delegate autonomous policies to a Redfish service. This session will review the v0.9 work-in-progress model.



# Policy model for Control Loops

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## Disclaimer

- The information in this presentation represents a snapshot of work in progress within the DMTF.
- This information is subject to change without notice. The standard specifications remain the normative reference for all information.
- For additional information, see the Distributed Management Task Force (DMTF) website.



## Contents

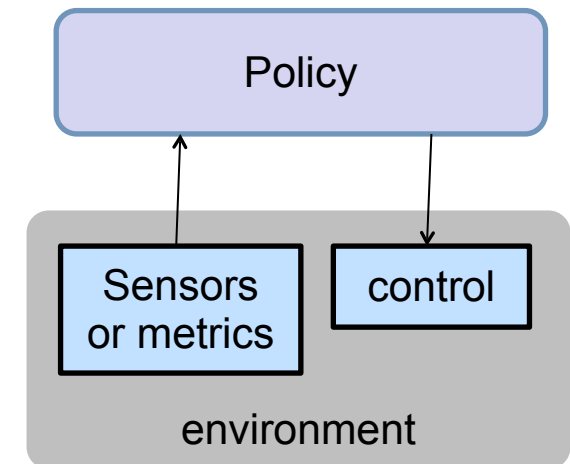
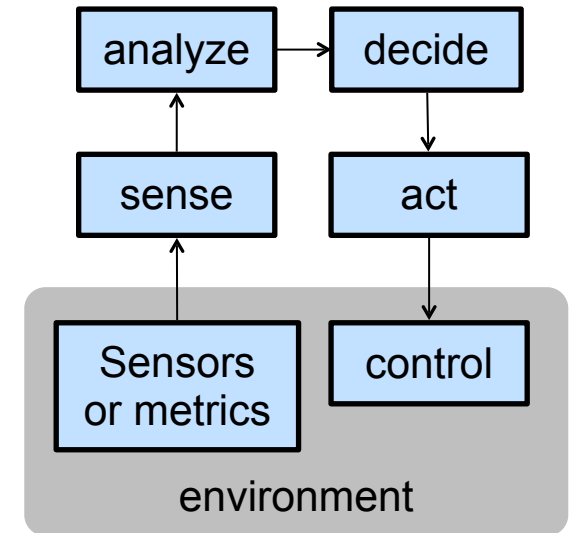
- Policy concepts: control loops and delegated policy
- Redfish policy model





## Control Loops

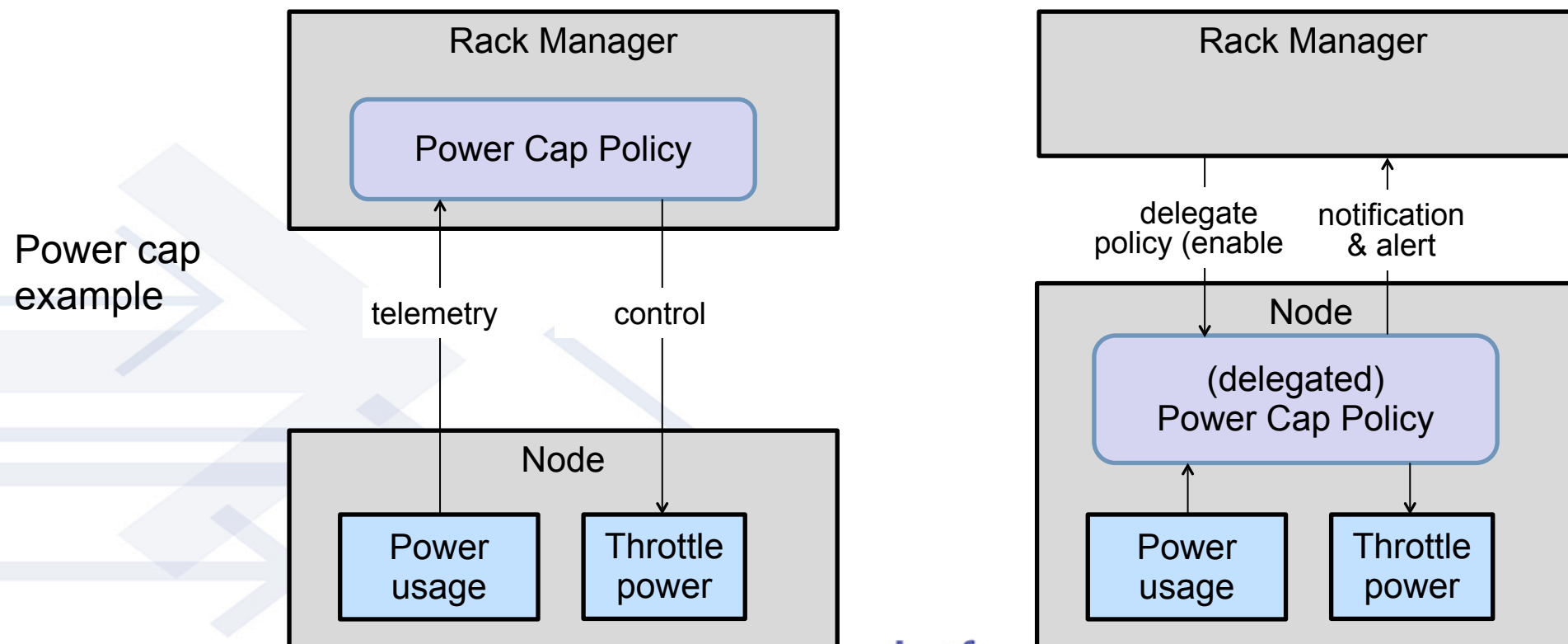
- Redfish resources exist for metrics, sensors and controls
- A control loop can be constructed between sensors/metrics and controls
  - Sense input(s)
  - Analyzed the input(s)
  - Decide on action(s), if any
  - Perform action(s) via control(s)
- The control loop can be structured as a policy resource
  - Analyze inputs and decide which reactions/controls to perform





## Policies can be Delegated

- The policy construct can be delegated down a hierarchy
- A delegated policy authorizes a node to enforce a policy, locally





## Survey of Policy Management Models

Details in Redfish Policy Proposal (2021)<sup>1</sup>

- DEN/COPS Policy Statements (1996-1998)
- DMTF/IETF Policy Framework (circa 2001) – introduced PDP and PEP
- TM Forum - GB922 R18.0.2 "Shared Information/Data Model" (2018)
- ETSI - Context-Aware Policy Management Gap Analysis (2018)
- ONF - The Policy Framework for ONOS (2019)
- DMTF DSP1048 - Network Policy Management Profile (2021)
- ETSI – GR NFV-IFA042 v4.1.1 "Policy Model" (2021)

<sup>1</sup>Redfish Policy Proposal - [https://www.dmtf.org/sites/default/files/Policy\\_Model\\_Proposal\\_v10.pdf](https://www.dmtf.org/sites/default/files/Policy_Model_Proposal_v10.pdf)



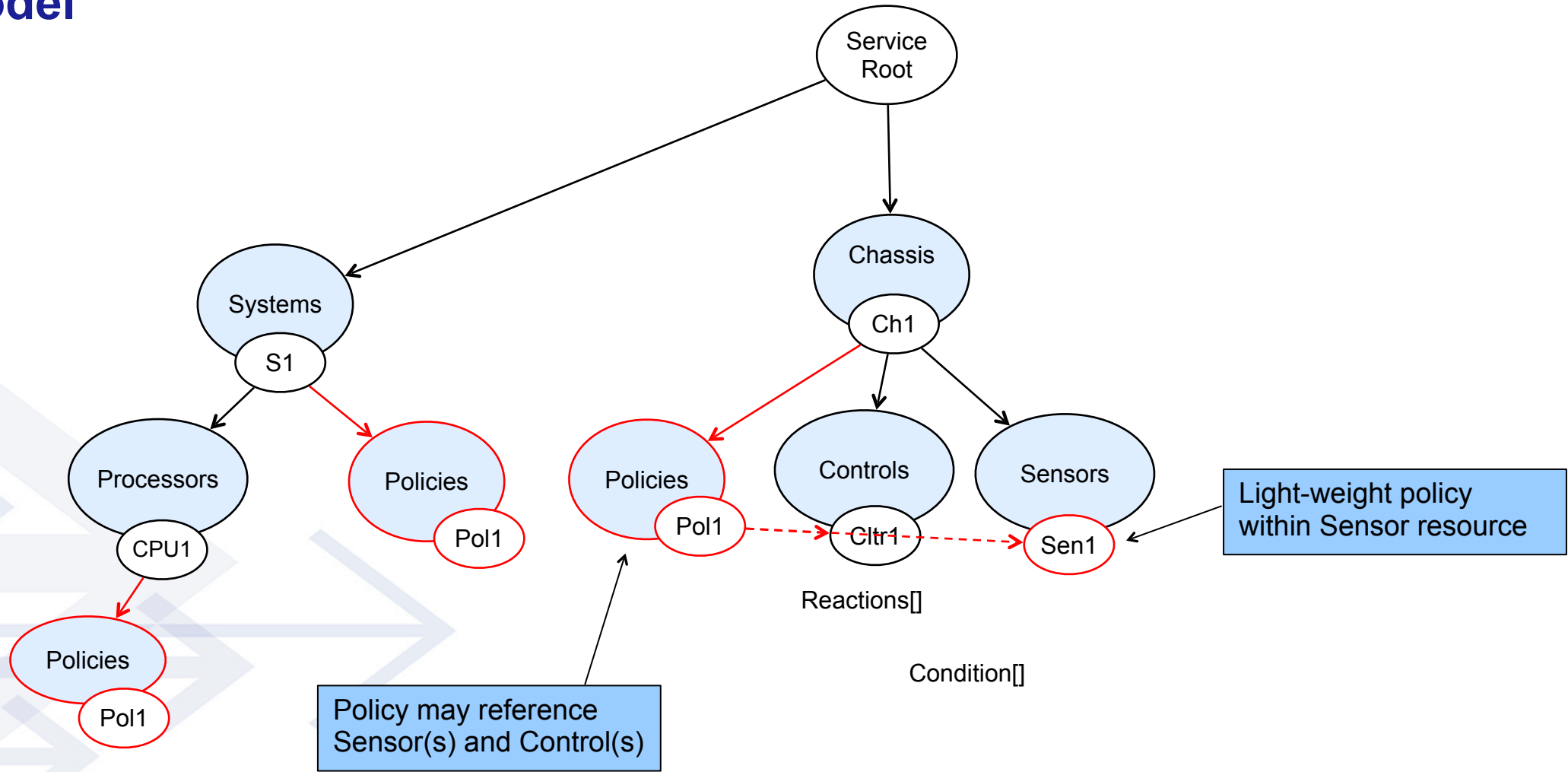
## Redfish Policy Model Requirements

- **Policy**
  - Can have multiple conditions and reactions
  - Can be subordinate to multiple resources (System, Chassis, Manager, etc)
  - Provides notification of policy exceptions or issues
- **Conditions and Reactions**
  - Can reference Sensor and Control resources, when applicable
  - Conditions can be local or remote (i.e. on another Redfish service)
  - Reactions can be delayed
- **Simple policy**
  - Ability to include light-weight policy (a single reaction) in the Sensor resource





# Policy Model





## Policy Resource

```
{
  "@odata.type": "#Policy.v1_0_0.Policy",
  "Name": "Policy for primary supply pressure",
  "Id": "PrimarySupplyPressurePolicy",
  "PolicyEnabled": true,
  "PolicyTriggered": false,
  "Status": {
    "State": "Enabled",
    "Health": "OK"
  },
  "PolicyConditions": [
    {
      "PolicyConditionType": ". . .",
      ...
    }
  ],
  "PolicyReactions": [
    {
      "Control": "/redfish/v1/Chassis/CDU/Controls/PowerUsage",
      "SetPoint": 0
    },
    {
      "CommonReaction": "SendEvent"
    }
  ],
  "@odata.id": "/redfish/v1/Chassis/CDU/Policies/PrimarySupplyPressurePolicy"
}
```



## PolicyConditionType's - Sources for a Policy Condition

- Policy condition can be local or from a remote source (peer)
- Policy condition can be a sensor, a property or an event

| PolicyConditionType  | Properties                                                                   |
|----------------------|------------------------------------------------------------------------------|
| <b>Sensor</b>        | Sensor (resource), Threshold (per Threshold object)                          |
| <b>Threshold</b>     | Property (resource property), PropertyValue, PropertyStringValue, Activation |
| <b>Event</b>         | MessageKey, OriginOfCondition                                                |
| <b>PeerSensor</b>    | PeerSource, Sensor, TriggerThreshold                                         |
| <b>PeerThreshold</b> | PeerSource, Property, PropertyValue, Activation                              |
| <b>PeerEvent</b>     | PeerSource, MessageKey, OriginOfCondition                                    |



## Policy - Sensor

```
{
  "@odata.type": "#Policy.v1_0_0.Policy",
  "Name": "Policy for primary supply pressure",
  "Id": "PrimarySupplyPressurePolicy",
  "PolicyEnabled": true,
  "PolicyTriggered": false,
  "Status": {
    "State": "Enabled",
    "Health": "OK"
  },
  "PolicyConditions": [
    {
      "PolicyConditionType": "Sensor",
      "Sensor": "/redfish/v1/Chassis/CDU/Sensors/PrimarySupplyPressure",
      "TriggerThreshold": "UpperCritical"
    }
  ],
  "PolicyReactions": [
    {
      "Control": "/redfish/v1/Chassis/CDU/Controls/PowerUsage",
      "SetPoint": 0
    },
    {
      "CommonReaction": "SendEvent"
    }
  ],
  "@odata.id": "/redfish/v1/Chassis/CDU/Policies/PrimarySupplyPressurePolicy"
}
```



## Policy - Peer Sensor

### PeerSource1

```
{
  "@odata.id": "/redfish/v1/PeerService/PeerSources/PeerSource1",
  "@odata.type": "#PeerSource.v1_0_0.PeerSource",
  "Id": "PeerSource1",
  "Name": "PeerSource One",
  "HostName": "https://Someserver.Contoso.com/redfish/v1",
    "UserName": "root",
  "Password": null,
  "Links": {
    "ConnectionMethod": {
      "@odata.id": "/redfish/v1/PeerService/
ConnectionMethods/ConnectionMethod1"
    },
    "ResourcesAccessed": [
      {
        "@odata.id": "/redfish/v1/Managers/1"
      }
    ]
  }
}
```

```
{
  "@odata.type": "#Policy.v1_0_0.Policy",
  "Name": "Policy for primary supply pressure",
  "Id": "PeerPrimarySupplyPressurePolicy",
  "PolicyEnabled": true,
  "PolicyTriggered": false,
  "Status": {
    "State": "Enabled",
    "Health": "OK"
  },
  "PolicyConditions": [
    {
      "PolicyConditionType": "PeerSensor",
      "Peer": "/redfish/v1/PeerService/PeerSources/PeerSource1",
      "Sensor": "/redfish/v1/Chassis/CDU/Sensors/PrimarySupplyPressure",
      "TriggerThreshold": "UpperCritical"
    }
  ],
  "PolicyReactions": [
    {
      "Control": "/redfish/v1/Chassis/CDU/Controls/PowerUsage",
      "SetPoint": 0
    },
    {
      "CommonReaction": "SendEvent"
    }
  ],
  "@odata.id": "/redfish/v1/Chassis/CDU/Policies/PeerPrimarySupplyPressurePolicy"
}
```



## Policy - Threshold

```
{
  "@odata.id": "/redfish/v1/Chassis/CDU/Policies/PeerPrimarySupplyPressurePolicy",
  "@odata.type": "#Policy.v1_0_0.Policy",
  "Name": "Policy for primary supply pressure",
  "Id": "PrimarySupplyPressurePolicy",
  "PolicyEnabled": true,
  "PolicyTriggered": false,
  "Status": {
    "State": "Enabled",
    "Health": "OK"
  },
  "PolicyConditions": [
    {
      "PolicyConditionType": "Threshold",
      "Property": "/redfish/v1/Chassis/CDU/Sensors/PrimarySupplyPressure#/Reading",
      "PropertyValue": 1400,
      "Activation": "Increasing"
    }
  ],
  "PolicyReactions": [
    {
      "Control": "/redfish/v1/Chassis/CDU/Controls/PowerUsage",
      "SetPoint": 0
    },
    {
      "Reaction": "SendEvent"
    }
  ]
}
```



## Policy - Peer Event

```
{
  "@odata.id": "/redfish/v1/Chassis/CDU/Policies/PeerLeakDetectionPolicy",
  "@odata.type": "#Policy.v1_0_0.Policy",
  "Name": "Policy for leak detection",
  "Id": "LeakDetectionPolicy",
  "PolicyEnabled": true,
  "PolicyTriggered": false,
  "Status": {
    "State": "Enabled",
    "Health": "OK"
  },
  "PolicyConditions": [
    {
      "PolicyConditionType": "Event",
      "EventPeerSource": "PeerSource1",
      "MessageKey": "...",
      "OriginOfCondition": "..."
    }
  ],
  "PolicyReactions": [
    {
      "Control": "/redfish/v1/Chassis/CDU/Controls/PowerUsage",
      "SetPoint": 0
    },
    {
      "CommonReaction": "SendEvent"
    }
  ]
}
```



## Simple Policy - within Sensor resource

```
{
  "@odata.type": "#Sensor.v1_9_0.Sensor",
  "Id": "PrimarySupplyPressure",
  "Name": "Primary Supply Pressure",
  "ReadingType": "PressurekPa",
  "Status": { "State": "Enabled", "Health": "OK" },
  "Reading": 827,
  "ReadingUnits": "kPa",
  ...
  "Thresholds": {
    "UpperCritical": {
      "Reading": 1380,
      "Activation": "Increasing",
      "DwellTime": "PT1M",
      "PolicyReaction": {
        {
          "Control": "/redfish/v1/Chassis/CDU/Controls/PowerUsage",
          "SetPoint": 0
        }
      }
    }
  }
}
```





## Call to Actions

- Review and profile feedback on the Redfish Policy Model WIP
  - DMTF Feedback portal





# *Backup*





## Example Sensor

### Primary Supply Pressure Sensor

```
{
  "@odata.type": "#Sensor.v1_9_0.Sensor",
  "Id": "PrimarySupplyPressure",
  "Name": "Primary Supply Pressure",
  "ReadingType": "PressurekPa",
  "Status": { "State": "Enabled", "Health": "OK" },
  "Reading": 827,
  "ReadingUnits": "kPa",
  "ReadingRangeMin": 0,
  "ReadingRangeMax": 1500,
  "ReadingBasis": "Zero",
  "SensingInterval": "PT5S",
  "PhysicalContext": "LiquidInlet",
  "Thresholds": {
    "UpperCritical": {
      "Reading": 1380,
      "Activation": "Increasing",
      "DwellTime": "PT1M"
    },
    "UpperCaution": {
      "Reading": 1240,
      "Activation": "Increasing",
      "DwellTime": "PT1M"
    }
  },
  "@odata.id": "/redfish/v1/Chassis/CDU/Sensors/PrimarySupplyPressure",
}
```

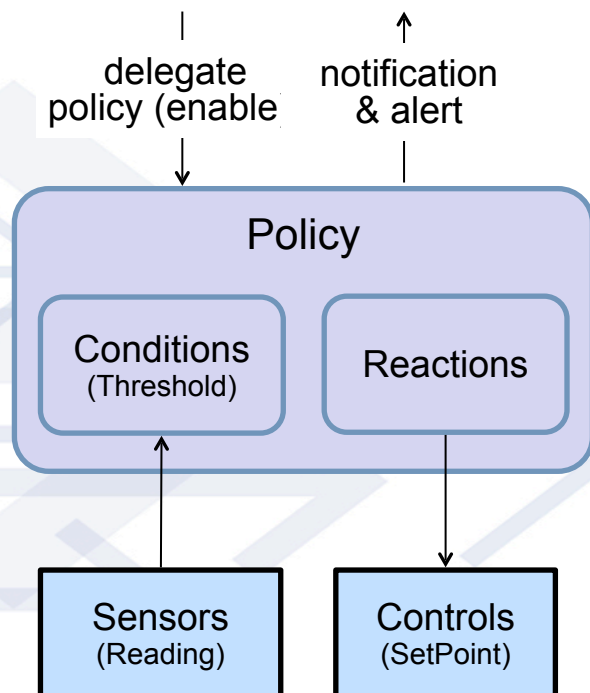
# Redfish Policy requirements

## Delegated Policy

- Policy schedule
- Conditions
  - dwell time
- Reactions
- Time to achieve
- Policy exception actions

## Notification & alerts

- Condition triggered (event?)
- Policy triggered (event?, prop?)
- Policy exception (event?)
  - Unable to achieve
- Invoking reaction (event?)
- Loss of sensor(s)



Added since previous WIP

- Delegated Power Limit Policy example
  - If power usage exceeds X, use delegated controls to reduce power usage below X within 50 ms (achieve goal within a timeframe)
  - If unable to achieve, notify the delegator
- Additional Policy Variations
  - Multiple conditions
    - Need to indicate AnyOf, AllOf, etc
  - Multiple reactions
    - Priority of policy reaction
    - Simultaneous vs stepwise reactions
- Remote sensors and controls
  - Either the sensor or control or both can be on another Redfish service
- Simple sensor policy
  - A single policy reaction within a sensor threshold